



# Nonlinear and Adaptive Control Design

*Miroslav Krstic, Ioannis Kanellakopoulos, Petar V. Kokotovic*

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**Nonlinear and Adaptive Control Design** Miroslav Krstic, Ioannis Kanellakopoulos, Petar V. Kokotovic  
Using a pedagogical style along with detailed proofs and illustrative examples, this book opens a view to the largely unexplored area of nonlinear systems with uncertainties. The focus is on adaptive nonlinear control results introduced with the new recursive design methodology--adaptive backstepping. Describes basic tools for nonadaptive backstepping design with state and output feedbacks.

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